

# GRK Ring Lecture: Deformation Theory, Part II

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## Set up:

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Throughout:

- ▶ Let  $k$  be a field,
- ▶  $X_0$  a  $k$ -scheme of finite type,
- ▶  $R$  a local noetherian ring with residue field  $R/\mathfrak{m}_R = k$ .

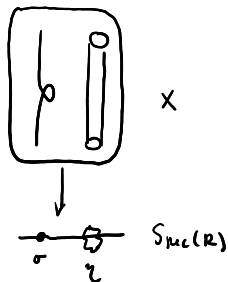
We seek to understand **deformations** of  $X_0$  over the ring  $R$ .

This are pairs  $(X, \varphi)$  where  $X$  is a **flat**  $R$ -scheme of finite type, and  $\varphi : X_0 \rightarrow X \otimes_R k$  is an isomorphism.

## Too difficult

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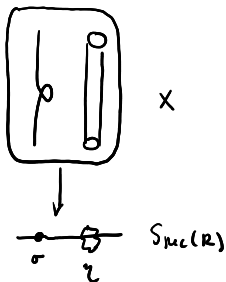
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That is **far too difficult for us**, at least at the moment! What is a simpler choice for the ring  $R$ ?

## The ring of dual numbers

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We work over the **ring of dual numbers**  $R = k[\epsilon]$ , where  $\epsilon$  is a formal symbol subject to  $\epsilon^2 = 0$ .

This is a **local Artin ring** with residue field  $k$ . It also has a  $k$ -algebra structure. The spectrum is a singleton  $\{\sigma\}$ , with a tangent vector attached.



Deformations of  $X_0$  over the ring  $R = k[\epsilon]$  are called **first-order deformations**.

## Deformations over dual numbers

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Let  $(X, \varphi)$  be a deformation over the dual numbers  $R = k[\epsilon]$ . It sits in a cartesian square

$$\begin{array}{ccc} X_0 & \longrightarrow & X \\ \downarrow & & \downarrow \\ \text{Spec}(k) & \longrightarrow & \text{Spec}(R). \end{array}$$

Hence the inclusion  $X_0 \subset X$  is a **homeomorphism**, so there is **no topology** left in our problem!

## Deformations over dual numbers

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Flatness ensures that in the exact sequence

$$0 \longrightarrow \mathcal{I} \longrightarrow \mathcal{O}_X \longrightarrow \mathcal{O}_{X_0} \longrightarrow 0,$$

the ideal is  $\mathcal{I} = k\epsilon \otimes_k \mathcal{O}_{X_0} = \epsilon \mathcal{O}_{X_0}$ .

In particular  $\mathcal{O}_X$  is an **extension** of  $\mathcal{O}_{X_0}$  by  $\mathcal{I} = \epsilon \mathcal{O}_{X_0}$ , viewed as coherent sheaves on  $X$ .

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We would prefer to have extensions with **coherent sheaves on  $X_0$** !



## Kähler differentials

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Recall that each  $A$ -algebra  $B$  comes with a  $B$ -module of **Kähler differentials**  $\Omega_{B/A}^1$ , defined by the short exact sequence

$$0 \longrightarrow \Omega_{B/A}^1 \longrightarrow (B \otimes_A B)/I^2 \longrightarrow (B \otimes_A B)/I \longrightarrow 0$$

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Similar definition applies for morphisms of schemes. In particular we get a quasicoherent sheaf  $\Omega_{X_0/k}^1$ . The dual

$$\Theta_{X_0/k} = \underline{\text{Hom}}(\Omega_{X_0/k}^1, \mathcal{O}_{X_0})$$

is the **tangent sheaf**.

## The standard exact sequence

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The  $k$ -structure on dual numbers gives  $X_0 \rightarrow X \rightarrow \text{Spec}(k)$ , yields **standard exact sequence**

$$\dots \rightarrow \mathcal{I}/\mathcal{I}^2 \rightarrow \Omega_{X/k}^1 \otimes \mathcal{O}_{X_0} \rightarrow \Omega_{X_0/k}^1 \rightarrow \Omega_{X_0/X}^1 \rightarrow 0,$$

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with for Kähler differentials. The map on the left is  $[f] \mapsto df \otimes 1$ .

**Fact:** If the scheme  $X_0$  is reduced and generically smooth, the map  $\mathcal{I}/\mathcal{I}^2 \rightarrow \Omega_{X/k}^1$  is injective. In any case,  $\Omega_{X_0/X}^1 = 0$ .

Suppose from now that  $X_0$  is reduced and generically smooth. The deformation  $(X, \varphi)$  gives an **extension**

$$0 \longrightarrow \mathcal{I}/\mathcal{I}^2 \longrightarrow \Omega_{X/k}^1 \otimes \mathcal{O}_{X_0} \longrightarrow \Omega_{X_0/k}^1 \longrightarrow 0$$

of coherent sheaves on  $X_0$ . Yields **Yoneda class**

$$[\Omega_{X/k}^1 \otimes \mathcal{O}_{X_0}] \in \text{Ext}^1(\Omega_{X_0/k}^1, \mathcal{O}_{X_0}).$$

This is called the **Kodaira–Spencer class**.

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**Theorem.** *The mapping  $(X, \varphi) \mapsto [\Omega_{X/k}^1 \otimes \mathcal{O}_{X_0}]$  identifies isomorphism classes of deformations of  $X_0$  over the dual numbers  $R = k[\epsilon]$  with vectors in  $\text{Ext}^1(\Omega_{X_0/k}^1, \epsilon \mathcal{O}_{X_0})$ .*

## Idea of proof

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We describe the inverse mapping:

Suppose we have an extension  $\mathcal{E}$ . The universal differential  $f \mapsto df$  defines via cartesian square

$$\begin{array}{ccccccc} & & \mathcal{O}_X & \longrightarrow & \mathcal{O}_{X_0} & & \\ & & \downarrow & & \downarrow d & & \\ 0 & \longrightarrow & \epsilon\mathcal{O}_{X_0} & \longrightarrow & \mathcal{E} & \longrightarrow & \Omega_{X_0/k}^1 \longrightarrow 0 \end{array}$$

an abelian sheaf  $\mathcal{O}_X$ . One specifies multiplication as in dual numbers, using  $d(fg) = fdg + gdf$ .

The ringed space  $X = (X_0, \mathcal{O}_X)$  becomes the total space of the deformation.

## Applications

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If  $X_0$  is smooth,  $\Omega_{X_0/k}^1$  is locally free, with dual  $\Theta_{X_0/k}$ , and we get an identification

$$\mathrm{Ext}^1(\Omega_{X_0/k}^1, \epsilon\mathcal{O}_{X_0}) = H^1(X_0, \Theta_{X_0/k}).$$

with cohomology of the tangent sheaf.

Cohomology groups are **more amenable to computations** than Ext groups. In any case, the zero class corresponds to the **constant deformation**

$$X = X_0 \otimes_k k[\epsilon]$$



**Corollary.** *If the scheme  $X_0$  is smooth and affine, then every deformation over  $R = k[\epsilon]$  is isomorphic to the constant deformation.*

Proof: Use Serre's Cohomological Criterion for affineness.

# Applications

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Proof: Use Serre's Cohomological Criterion for affineness.

**Corollary.** *Every deformation of the projective space  $X_0 = \mathbb{P}^n$  over  $R = k[\epsilon]$  is isomorphic to the constant deformation.*

Proof: Use the Euler sequence

$$0 \longrightarrow \mathcal{O}_{\mathbb{P}^n} \longrightarrow \bigoplus_{i=0}^n \mathcal{O}_{\mathbb{P}^n}(1) \longrightarrow \Theta_{\mathbb{P}^n/k} \longrightarrow 0.$$

**Corollary.** *Let  $X = C$  be a smooth curve of genus  $g \geq 2$ . Then the space of first order deformations has dimension  $d = 3g - 3$ .*

Proof: The structure sheaf has  $\chi(\mathcal{O}_C) = 1 - g$ . The **dualizing sheaf**  $\omega_C = \Omega_{C/k}^1$  has degree  $r = 2g - 2$ . Its inverse  $\mathcal{L} = \Theta_{C/k}$  has degree  $-r = 2 - 2g < 0$ . **Riemann–Roch** gives

$$-h^1(\mathcal{L}) = \chi(\mathcal{L}) = \deg(\mathcal{L}) + \chi(\mathcal{O}_C) = 3 - 3g.$$

## Historical starting point:

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This is the **starting point of algebraic geometry!** From Riemann's 1857 paper on abelian functions:

"... the corresponding class [...] depends on  $3g - 3$  continuous variables, which we shall call the **moduli** of the class."



Bernhard Riemann (1826–1866)

## Automorphisms and obstructions

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The **automorphisms group** of the extension

$$0 \longrightarrow \mathcal{I}/\mathcal{I}^2 \longrightarrow \Omega_{X/k}^1 \otimes \mathcal{O}_{X_0} \longrightarrow \Omega_{X_0/k}^1 \longrightarrow 0$$

is the Hom group

$$\mathrm{Hom}(\Omega_{X_0/k}^1, \epsilon\mathcal{O}_{X_0}) = \mathrm{Ext}^0(\Omega_{X_0/k}^1, \epsilon\mathcal{O}_{X_0}).$$

By our Theorem, this is also the automorphism group for every first-order deformation  $(X, \varphi)$ .

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We shall see later that the Ext group  $\mathrm{Ext}^2(\Omega_{X_0/k}^1, \epsilon \mathcal{O}_{X_0})$  contains the **obstructions** against higher-order deformations over rings like  $R = k[t]/(t^n)$ .

## Formal schemes

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Suppose  $X_0 = C$  is a smooth curve. Then the obstruction group

$$\mathrm{Ext}^2(\Omega_{X_0/k}^1, \epsilon\mathcal{O}_{X_0}) = H^2(X_0, \Theta_{X_0/k})$$

is zero, by Grothendieck's Vanishing result.

So one finds compatible deformations  $(X_n, \varphi_n)$  of  $X_0 = C$  over the rings  $R_n = k[t]/(t^{n+1})$ . This gives an inverse system of proper schemes  $\mathfrak{X} = (X_n)_{n \geq 0}$  over the complete local rings  $R = k[[t]]$ . This are the so-called **formal schemes**.

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**Does the formal  $R$ -scheme  $\mathfrak{X}$  come from an  $R$ -scheme  $X$ , such that  $X_n = X \otimes R_n$ ?**



## Grothendieck's Algebraization Theorem

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**Theorem.** *Suppose there is a compatible family  $(\mathcal{L}_n)$  of invertible sheaves on  $(X_n)$ , such that  $\mathcal{L}_0 \in \text{Pic}(X_0)$  is ample. Then there is a proper  $R$ -scheme  $X$  inducing the formal scheme  $\mathfrak{X}$ , unique up to unique isomorphism.*

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This holds for arbitrary formal schemes. In dimension one, each proper scheme is projective (Riemann–Roch). The obstruction to lift a class in  $\text{Pic}(X_n) = H^1(X_n, \mathcal{O}_{X_n}^\times)$  to the thickening  $X_{n+1}$  lies in  $H^2(C, \mathcal{O}_C) \otimes kt^{n+1}$ , which is zero!

So the  $d = 3g - g$  first-order deformations for  $C$  indeed give Riemann's moduli!

## The case of smooth affine schemes

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We now examine deformations over general local Artin rings  $R$  with residue field  $k$  and having a  $k$ -algebra structure.

**Lemma.** *If the scheme  $X_0$  is smooth and affine, then every deformation over  $R$  is constant.*

Proof: Saw this already for  $R = k[\epsilon]$ . In general, apply induction on  $\text{length}(R)$ , and use definition of smoothness.

## The case of smooth affine schemes

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Suppose that we have a deformation  $(X_{n-1}, \varphi_{n-1})$  of  $X_0$  over the ring  $R_{n-1} = k[t]/(t^n)$ .

Choose affine open covering  $X_0 = U_1 \cup \dots \cup U_r$ . On each  $U_i$  the deformation over  $R_{n-1}$  becomes constant. So they extend to  $R_n$ . On overlaps  $U_{ij}$  these differ by isomorphisms  $\varphi_{ij}$ .

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May not satisfy **cocycle condition**, but  $\varphi_{jk} \circ \varphi_{ij} = f_{ijk} \varphi_{ik}$  defines cocycle  $f_{ijk} \in \Gamma(U_{ijk}, \Theta_{X_0/k} \otimes kt^n)$ . Yields some cohomology class  $ob \in H^2(X_0, \Theta_{X_0/k})$ . Is the **obstruction** for changing the local isomorphisms so that global deformation arises via glueing.

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If  $\text{ob} = 0$ , the set of all deformations  $(X_n, \varphi_n)$  restricting to  $(X_{n-1}, \varphi_{n-1})$  is a **torsor** under  $H^1(X_0, \Theta_{X_0/k})$ .

## Formal smoothness for functors of Artin rings

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Let  $\text{Art}(k)$  be the category of local Artin rings  $R$  with residue field  $k$ . Consider the functor

$$h : \text{Art}(k) \longrightarrow (\text{Set})$$

that sends  $R$  to the set of isomorphism classes of deformations  $(X, \varphi)$  of the scheme  $X_0$  over the ring  $R$ .

**Theorem.** *Suppose that  $X_0$  is smooth and  $h^2(\Theta_{X_0/k}) = 0$ . Then the above functor is formally smooth.*

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Here **formal smoothness of functors** means  $h(A) \rightarrow h(A/I)$  is surjective for square-zero ideals, as in my first lecture. The result applies if  $X_0 = C$  is a proper smooth curve.



## K3 surfaces

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It also applies if  $X_0 = S$  is a **K3 surface** ( $c_1 = 0$  and  $b_2 = 22$ ).



Ernst Kummer  
(1810–1893)



Kunihiye Kodaira  
(1915–1997)



Erich Kähler  
(1906–2000)

Examples are quartic hypersurfaces  $S \subset \mathbb{P}^3$ , or the resolution of singularities for  $S \rightarrow A/\{\pm 1\}$ .

## K3 surfaces

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Although deformations of the scheme  $X_0$  are unobstructed, there are obstructions for deforming invertible sheaves  $\mathcal{L}_0$ . They lie in  $H^2(X_0, \mathcal{O}_{X_0}) = k$ .

Over  $k = \mathbb{C}$ , this leads to **non-algebraic K3 surfaces**. Then the field of meromorphic functions  $f : S \dashrightarrow \mathbb{C}$  has transcendence degree  $\text{trdeg} < 2$ .

For general ground fields  $k$ , this yields formal families  $\mathfrak{X} \rightarrow \text{Spec}(k[[t]])$  of K3 surfaces that are **not algebraizable**.

**Thank you very much for the attention!**